

FEA Capturing Both Brittle and Ductile Crack Propagation

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Abstract: A finite element analysis methodology was developed to simulate brittle crack initiation, ductile or brittle crack propagation and ductile crack arrest in a single simulation using ABAQUS. Ductile fracture was modeled by employing element deletion when the equivalent plastic strain reached a critical value. Within the same FEM, brittle fracture was modeled by incorporating cohesive behavior between contact surfaces defined along the expected crack face. While this method was not as accurate as an FEM incorporating J integral calculations, its simplicity allowed simultaneous incorporation of brittle and ductile fracture. The material properties for the cohesive behavior at the crack tip were calibrated for crack initiation while the material properties for the remainder of the crack faces were calibrated for crack arrest.

Keywords: Crack Propagation, Crack Arrest, Fracture

1. Introduction

Quest Integrity and IHI implemented and evaluated a new finite element analysis methodology to simulate brittle crack initiation, brittle or ductile crack propagation and brittle or ductile crack arrest in a single simulation using commercially available software. Many current methodologies were available, however none included all the features listed above. For example, Tanguay *et al* simulated ductile crack propagation using finite element analysis (FEA) and identified a posteriori the crack length corresponding to unstable brittle failure using a modified Weibull stress approach. As another example, Quest Reliability divided the analysis into a sequence of meshes, each with a different crack length and a crack tip spider mesh that facilitated J integral calculation. This approach did not incorporate ductile fracture.

For the new methodology developed in this project, ductile crack propagation was modeled by employing element deletion when the equivalent plastic strain reached a critical value. The critical equivalent plastic strain varied with triaxiality, as proposed by Bao, Wierzbicki, et al (see Figure 1). Their method was simple and practical yet accurate. Within the same finite element model (FEM), brittle crack propagation and arrest were modeled using contact defined along the expected crack face, incorporating cohesive traction-separation behavior. While this method was not as accurate as an FEM incorporating J integral calculations, its simplicity allowed simultaneous incorporation of brittle and ductile fracture. The material properties for the cohesive behavior at the crack tip were calibrated for crack initiation while the cohesive material properties for the remainder of the crack were calibrated for crack arrest.

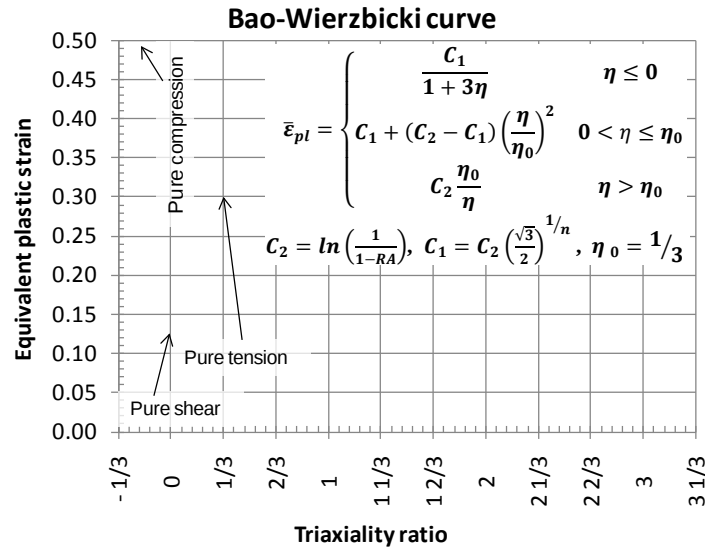


Figure 1. Equivalent plastic strain vs. triaxiality, as proposed by Bao, Wierzbicki, et al, for RA=30%

2. Objective

The objective of this project was to implement, examine and demonstrate a preliminary FEA-based methodology to simulate brittle crack initiation, followed by brittle or ductile propagation and brittle or ductile crack arrest using the Bao-Wierzbicki ductile failure criteria and cohesive contact.

3. Overview of the simulation

A, large thin C(T) test specimen was simulated because crack arrest was typically well characterized by this specimen shape. The large, thin size was chosen for 3 reasons:

- In a real arrest test (such as the SE(T) test), a temperature gradient was imposed on the specimen which required a specimen large enough to facilitate temperature gradients. The FEM model was made large to mimic the real arrest test.
- With a large model, reflections of acoustic waves off of specimen boundaries were minimized.
- In a small specimen, crack propagation speed may be high enough that the crack never arrested due to inertial effects. In contrast, the large specimen size allowed the crack velocities to stabilize and arrest before out-running the specimen width.

Temperature gradients (and thus toughness values) were chosen such that the initial crack propagation was brittle, followed by brittle or ductile crack propagation and finally, brittle or

ductile crack arrest. This scenario was chosen because the scenario with ductile initiation followed by brittle propagation was more difficult to simulate as described below.

As a ductile crack propagates, the number of potential cleavage nucleation sites experiencing high tensile stresses (characterized by the Weibull stress) increased, according to the Beremin model. When the Weibull stress reached a critical value (i.e. the crack “sampled” a sufficient number of nucleation sites experiencing high stresses), ductile crack propagation changed to brittle crack propagation. To capture this phenomenon, the Weibull stress must be calculated during each FEA increment and a message must be passed to the material model for each cohesive material point, indicating the onset of brittle propagation. Implementing this message passing in the finite element software would have required efforts beyond the scope of this project.

To avoid the above described difficulty, this project was limited to the simulation of brittle initiation followed by brittle or ductile arrest. To ensure this sequence, the simulated structure was subjected to a temperature gradient (colder at the crack initiation location, warmer at arrest location), much like the SE(T) test and temperature dependent toughness was incorporated into the model.

4. Material properties

ASTM A533B steel was chosen as the material for this project because this material has been researched extensively and therefore the material properties were readily available.

4.1 Mechanical properties

Figure 2 shows stress-strain curves for this material. The experimentally measured true stress vs. logarithmic plastic strain curve was reported by Haggag, *et al.* A von Mises plasticity model was used to model the nonlinear stress-strain response of the material.

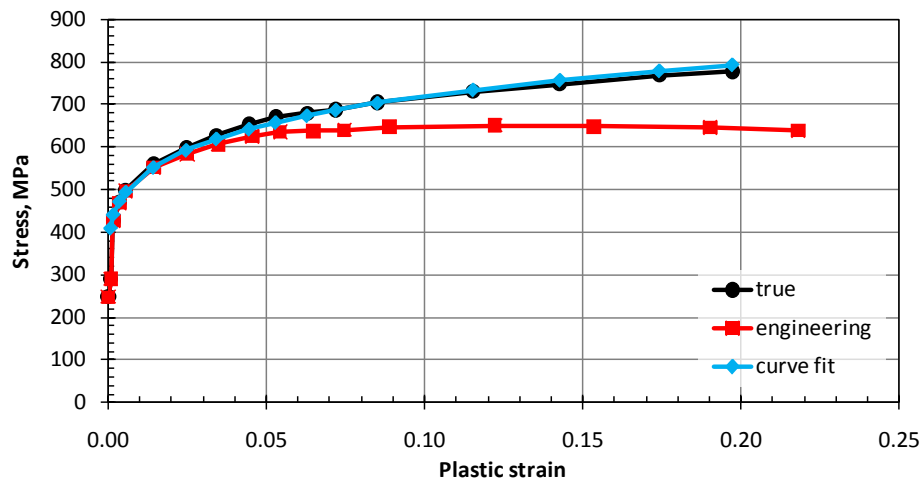


Figure 2. Stress strain curves for ASTM A533B reported by Haggag, *et al*

4.2 Transition curve for fracture toughness

The temperature dependent fracture toughness behavior was summarized as a pair of transition curves (temperature vs. toughness curves) which are shown in Figure 3. The curve for crack initiation was characterized by three regions:

- the lower shelf indicating brittle material behavior at lower temperatures, characterized by cleavage failure
- the upper shelf indicating ductile material behavior at higher temperatures by ductile tearing (void coalescence)
- a transition region between the upper and lower shelf

The transition curve for arrest toughness was similar to the curve for crack initiation, but was shifted as shown in Figure 3.

The upper shelf toughness, K_{IC} , was approximated based on J - R curves reported by Hiser (1993). The parameter J was determined following the methodology described in ASTM E1820-01.

The reference temperature, T_0 , was defined as the temperature at which the transition curve crossed $K_{IC} = 100 \text{ MPa m}^{0.5}$. The reference temperature, for crack initiation was -37.0°C . This value was the average of several values reported by Hiser (1990) for unirradiated ASTM A533B.

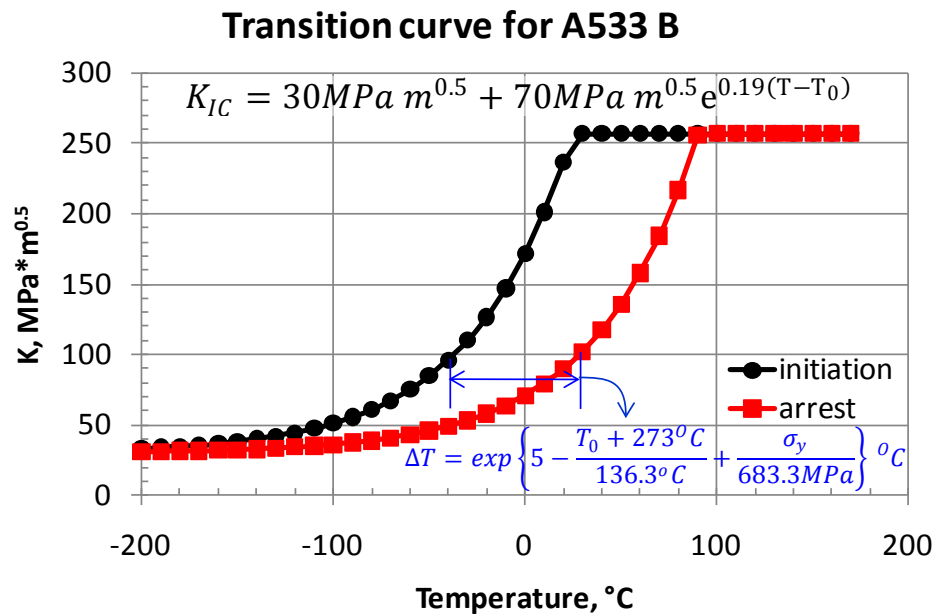


Figure 3. Temperature dependent brittle crack initiation, brittle crack arrest and ductile fracture toughness

The transition curve for crack initiation was calculated from T_0 using the equation described in ASTM E1921-05. The transition curve for crack arrest was calculated from the transition curve for crack initiation. The relationship between crack arrest and initiation was described by Wallin as a shift of T_0 . The shift was 65.4°C and the corresponding transition temperature for crack arrest was 28.4°C .

4.3 Bao-Wierzbicki model for ductile fracture

The Bao-Wierzbicki model (equivalent plastic strain vs. triaxiality curve), was calibrated so that K_I at crack initiation calculated from simulation and K_{Ic} from experiment matched. Jeong *et al* provided an approximation of the Bao-Wierzbicki curve (to be used when the experimentally measured curve is not available), in which RA was the reduction of area at fracture of a tensile test specimen and n was the hardening exponent of the stress-strain response as shown in Figure 2. The RA value was tuned so that FEM and experimental results for ductile fracture matched, resulting in $RA=30\%$. The tuning process is described in a later section. In contrast, Chaouadi and Fabry reported $RA=59\%$. This discrepancy is a well known phenomenon known as localization or mesh size sensitivity: in an FEA, simulated necking typically localizes to one or two elements in an FEA. In an experiment, necking length is material and geometry dependent. RA is closely related to the necking length and therefore RA differs between FEM and experiment.

5. Finite element model

A large, thin C(T) test specimen was simulated. Key dimensions were width, $W = 1.0\text{ m}$; crack length, $a = 0.5\text{ m}$ ($a/w = 0.5$); thickness, $B = 25.4\text{ mm}$. A half-symmetric finite element mesh of the specimen was constructed. The FEM is shown in Figure 4. The symmetry plane was located at half thickness and the thickness of the FEM model was 12.7 mm .

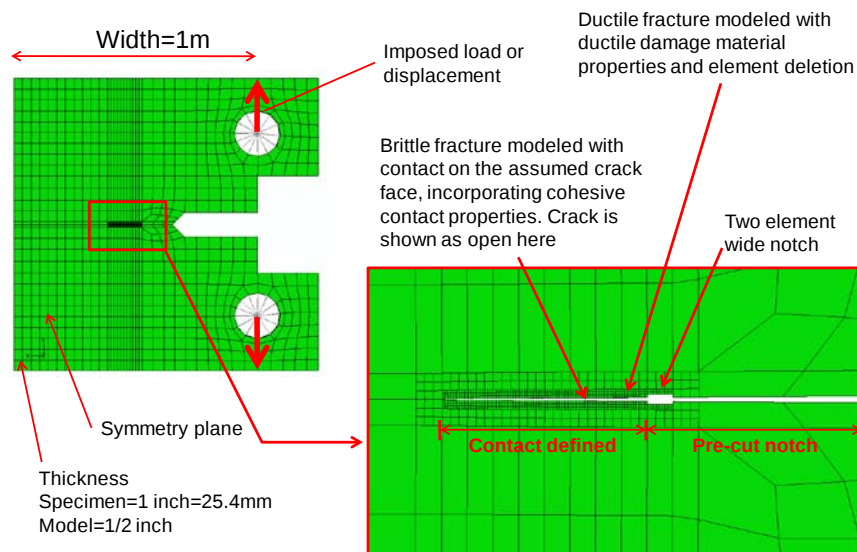


Figure 4. Finite element model

Brittle crack propagation and arrest was modeled using contact defined along the expected crack face, incorporating cohesive traction-separation behavior. The mesh was fine on either side of the “contact” faces with the mesh size increasing away from the “contact” faces. The element size in the fine mesh zone was 1.41 mm (9 elements through half thickness).

Real specimens are “pulled apart” by loading pins that slip into to the holes of the specimen. In the FEM, the loading pins were modeled as reference nodes that were kinematically coupled (rigidly attached) to the inner surface of the load pin hole. Out of plane displacements on one face of the model were restrained to implement half-symmetry.

Loads were applied over a time period ranging from 0.1 to 0.12 seconds . This load duration was chosen to achieve reasonable computer run times.

The simulation was performed using an explicit solver because an implicit solver would have diverged due to the incorporated brittle material behavior and element deletion. Noisy results due to acoustic effects were unavoidable and added extra effort for post-processing.

Constant mass scaling was used to decrease computer run times. The effect of mass scaling was not investigated but was expected to be minimal.

5.1 Implementation of fracture behavior

Ductile fracture was simulated using the following features (keywords) in Abaqus:

```
*PLASTIC
*DAMAGE INITIATION, CRITERION=DUCTILE
*DAMAGE EVOLUTION, TYPE=ENERGY
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With these features, “damage” initiated when elements experienced a critical equivalent plastic strain described by the Bao-Wierzbicki curve shown in Figure 1. When the equivalent plastic exceeded the critical value, the material responded with a softening stress vs. displacement behavior as shown in Figure 5. The dissipated energy, G_f , was specified as an input. When the material completely softened (separation= δ_0) the element was deleted from the mesh.

Within the same FEM, brittle fracture (initiation, propagation and arrest) was simulated using “contact” defined along the expected crack face, incorporating cohesive traction-separation behavior. The following features (keywords) in Abaqus were used:

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*COHESIVE BEHAVIOR
*DAMAGE INITIATION, CRITERION=MAXS
*DAMAGE EVOLUTION, TYPE=ENERGY
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The mesh was constructed as two halves, divided along the predicted crack face. The opposing crack face pairs were joined using the Abaqus “contact” feature in which the two opposing crack faces were initially “tied together” and separation was governed by a traction (tensile stress perpendicular to the crack face) vs. separation relationship. At the beginning of the simulation, the crack face pair was “tied” together. When the traction reached a critical value, σ_{max} , the contact faces separated and responded with softening traction vs. displacement

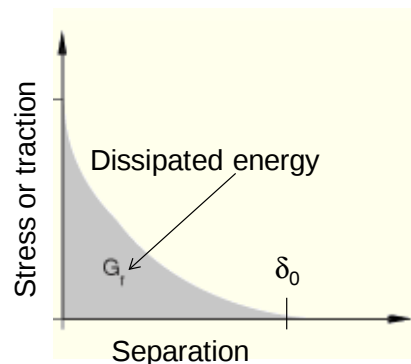


Figure 5. Softening behavior

behavior as shown in Figure 5. Note that both ductile softening and cohesive behavior employ the same softening (“damage”) model.

6. Material parameter calibration

Parameters for the material models were calibrated by matching simulated toughness results and experimental results. The following formulas from ASTM E1820-01 were used to correlate load(P), and toughness (K_{Ic} or K_{Jc}):

$$K_I = \frac{P}{B\sqrt{W}} f\left(\frac{a}{W}\right)$$

$$f\left(\frac{a}{W}\right) = \left(\frac{1 + \frac{a}{W}}{1 - \frac{a}{W}}\right)^2 \left[2.163 + 12.219\left(\frac{a}{W}\right) - 20.065\left(\frac{a}{W}\right)^2 + 0.9925\left(\frac{a}{W}\right)^3 + 20.609\left(\frac{a}{W}\right)^4 + 9.9314\left(\frac{a}{W}\right)^5 \right]$$

6.1 Ductile fracture

The ductile damage parameters (RA , G_f) were calibrated so that K_{Jc} from simulations matched the experimentally measured upper shelf toughness. Fracture initiation was defined as the instant when the first element was deleted from the mesh. The calibration results were $RA=30\%$ and $G_f = 10 \text{ kJ}$ (arbitrarily assumed). The load-displacement curve exhibited ductile response: the load continued to increase (with increased displacement) beyond crack initiation. On the free face, shear lips formed.

6.2 Brittle fracture

Cohesive behavior parameters (σ_{max} and G_f) were calibrated so that K_{Ic} from simulation matched the experimentally measured lower shelf toughness and various toughness points along the transition curve. Fracture initiation was defined by the peak in the load displacement curve. The load-displacement curve exhibited a brittle response: the load increased linearly and peaked, at which point the crack initiated, then the load dropped dramatically, immediately after crack initiation.

As a simplification, energy dissipation (G_f) was defined as

$$G_f = 0.1 \text{ Joule} (\sigma_{max} / \text{MPa})^2$$

Figure 6 plots σ_{max} vs. K_{Ic} obtained from several simulations. A linear line was fit to these points. The contact face at the initial crack tip was assigned σ_{max} and G_f corresponding to “initiation,” and the remainder of the crack face was assigned σ_{max} and G_f corresponding to “arrest.”

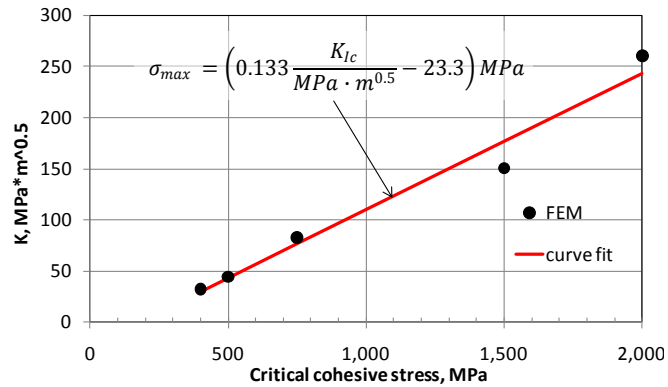


Figure 6. Calibration of critical stress for cohesive material properties and K

7. Crack arrest simulations

Simulations were performed to demonstrate that the methodology developed in this project can capture brittle crack initiation, followed by brittle or ductile propagation and brittle or ductile crack arrest.

In order to induce brittle initiation at the initial crack tip, a lower temperature (corresponding to lower shelf or transition region toughness) was assigned to this area. A temperature gradient, increasing in the direction of crack propagation was also assigned. Figure 7 shows the details of the temperature gradient. The temperature gradients were adjusted to achieve either brittle or ductile crack arrest.

7.1 Brittle crack arrest

The temperature at the initial crack tip was -100°C (where $K_{Ic} = 51.1 \text{ MPa m}^{0.5}$). The load – displacement response, and a snapshot of the simulation for the brittle arrest simulation are shown in Figure 8 and Figure 9. The load-displacement curve exhibited a brittle response: the load increased linearly and peaked at 119 kN , at which point the crack initiated, then the load dropped dramatically, immediately after crack initiation. The crack propagated very quickly and arrested at 150 mm from the point of initiation (where the temperature was -50.4°C and $K_{Ia} = 45.7 \text{ MPa m}^{0.5}$).

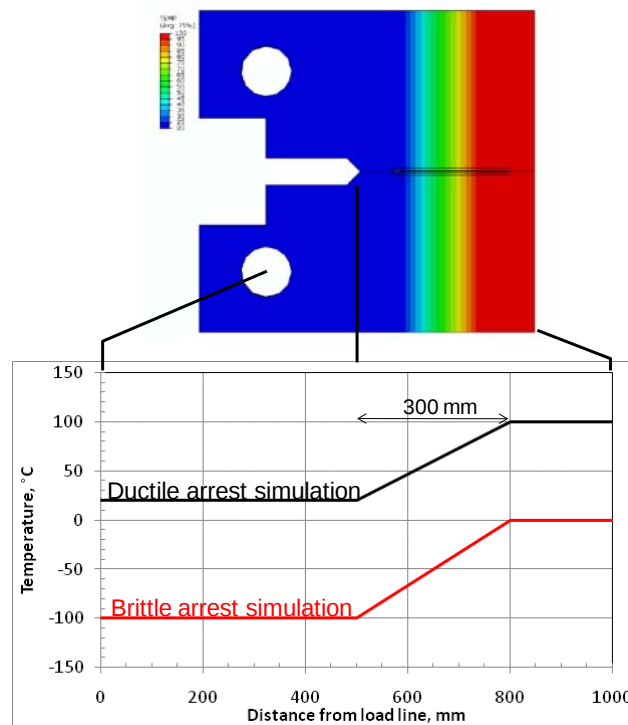


Figure 7. Temperature gradient

7.2 Ductile crack arrest

The temperature at the initial crack tip was 20°C (where $K_{Ic} = 236.7 \text{ MPa m}^{0.5}$). The load – displacement response and snapshots of the simulation for the ductile arrest simulation are shown in Figure 10 through Figure 13. The load-displacement curve exhibited ductile response: the load increased almost linearly to a load of 382 kN when the crack initiated and the load continued to increase (with increased load) beyond crack initiation. The crack propagated very quickly at first but slowed down considerably. The crack arrested at 334 mm from the point of initiation (where the temperature was 100°C and $K_{Ia} = 256.8 \text{ MPa m}^{0.5}$). Shear lips formed in the vicinity of the crack arrest site, on the free face.

This simulation demonstrated that initiation and ductile arrest can be simulated using the methodology developed in this project. The configuration of the specimen for the ductile arrest case (temperature gradient and loading scenario) may have seemed unrealistic. However this methodology may be useful for analyzing structures that incorporate crack arresting components, in particular calculating the failure load of such components.

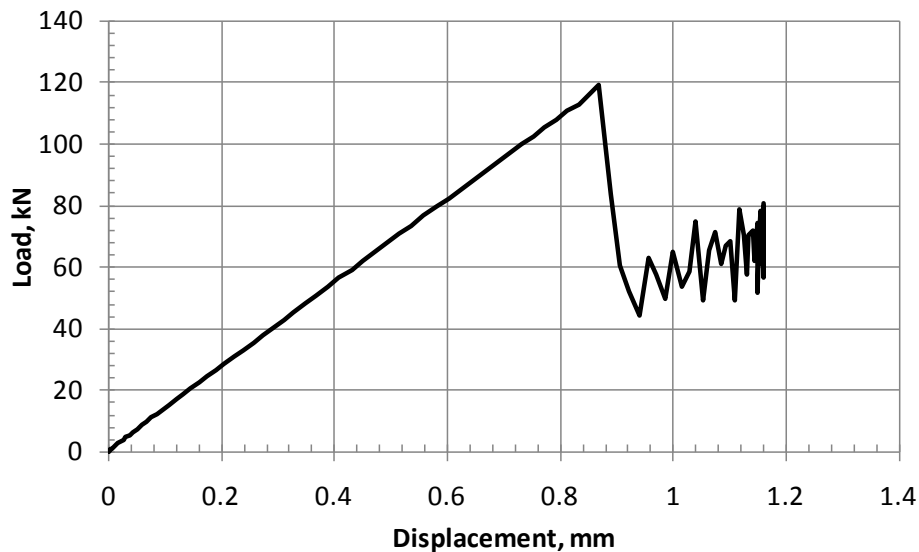
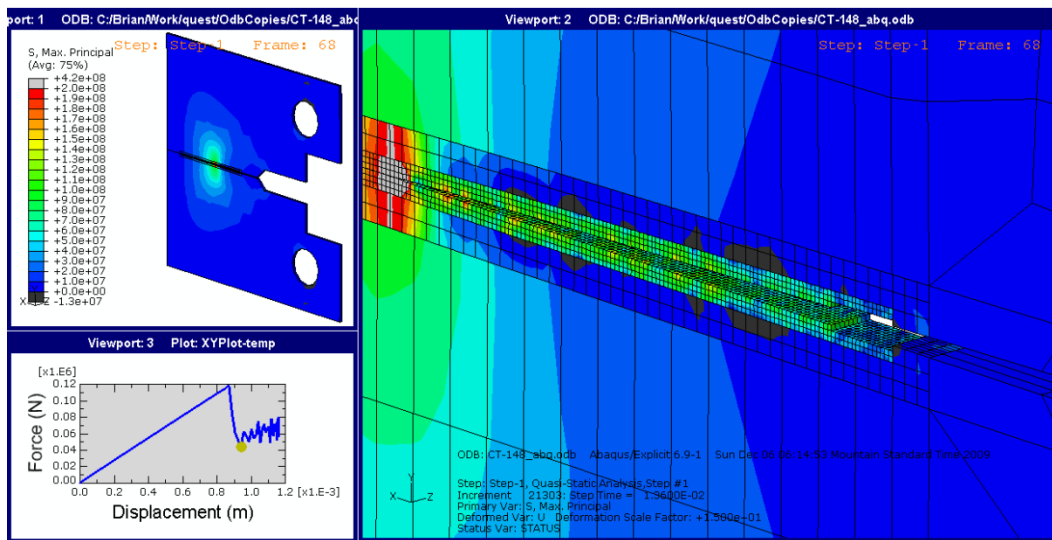


Figure 8. Load – displacement response, model with temperature gradient from -100 to 0°C



At brittle crack arrest

Figure 9. Snapshot, model with temperature gradient from -100 to 0°C, maximum principal stress (Pa), looking at the symmetry face. Deformations magnified 15x.

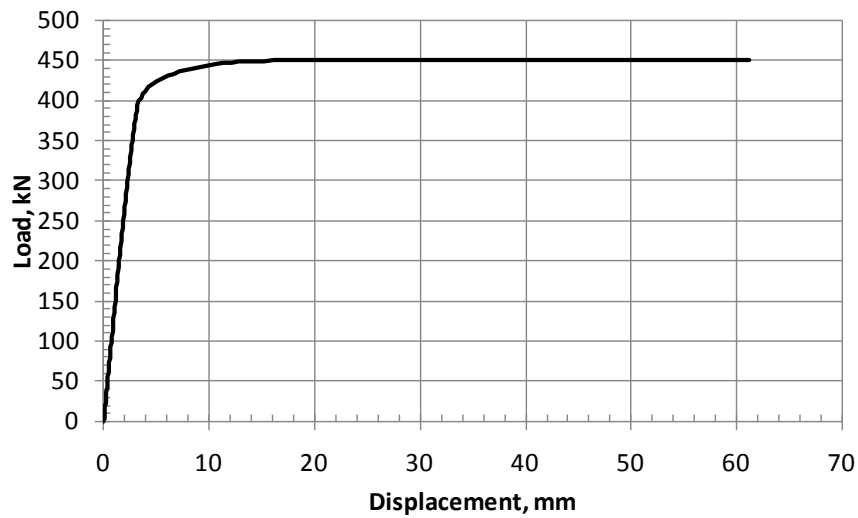
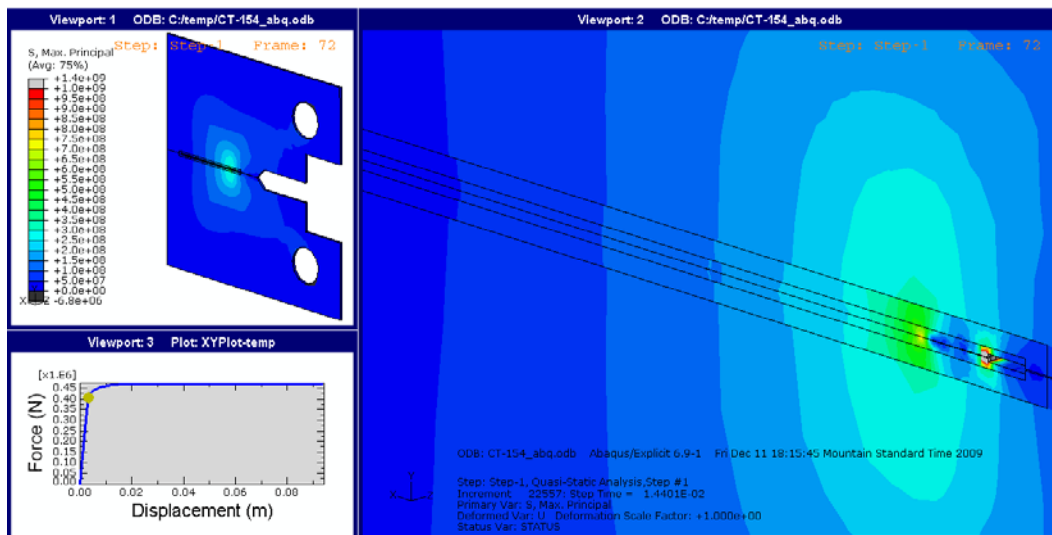
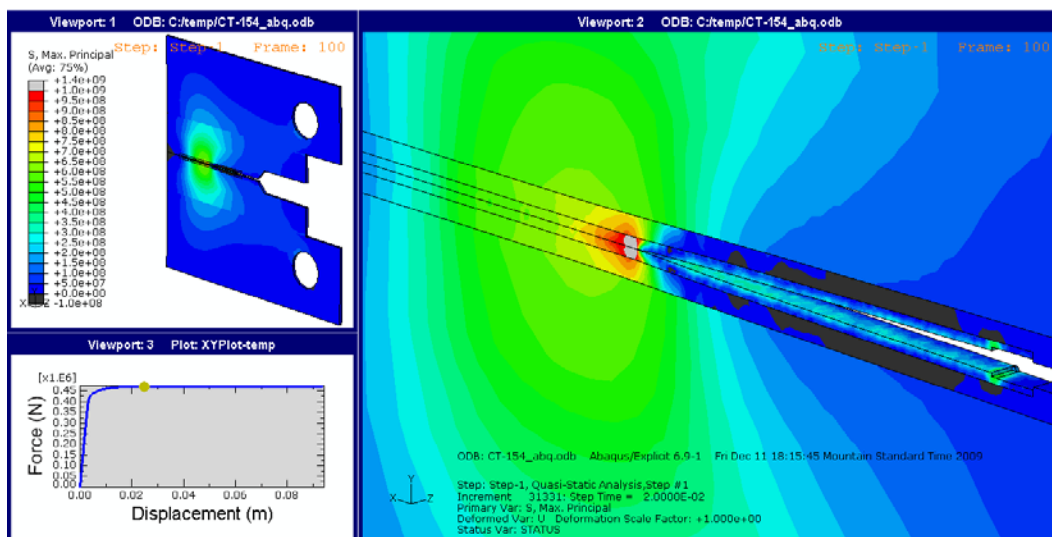


Figure 10. Load – displacement response, model with temperature gradient from 20 to 100°C

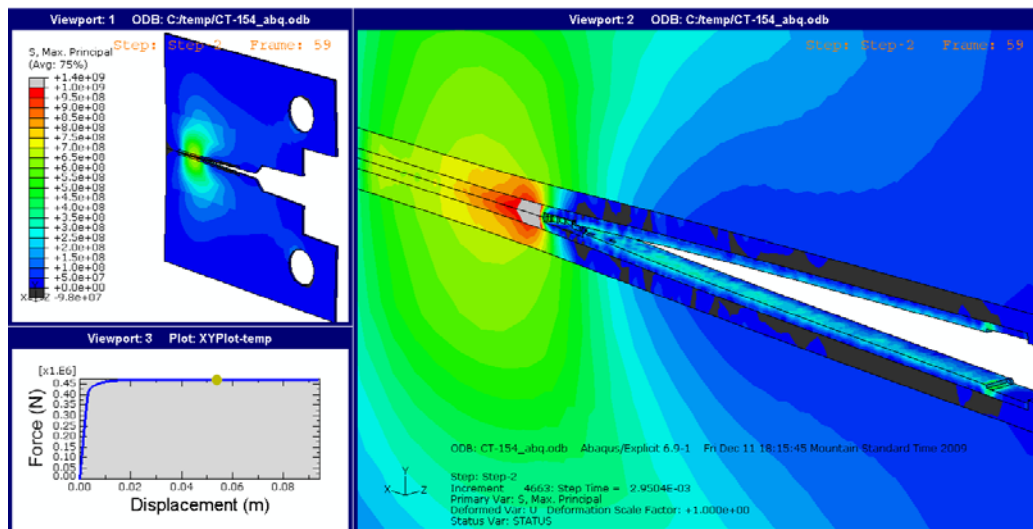


Immediately after brittle crack initiation

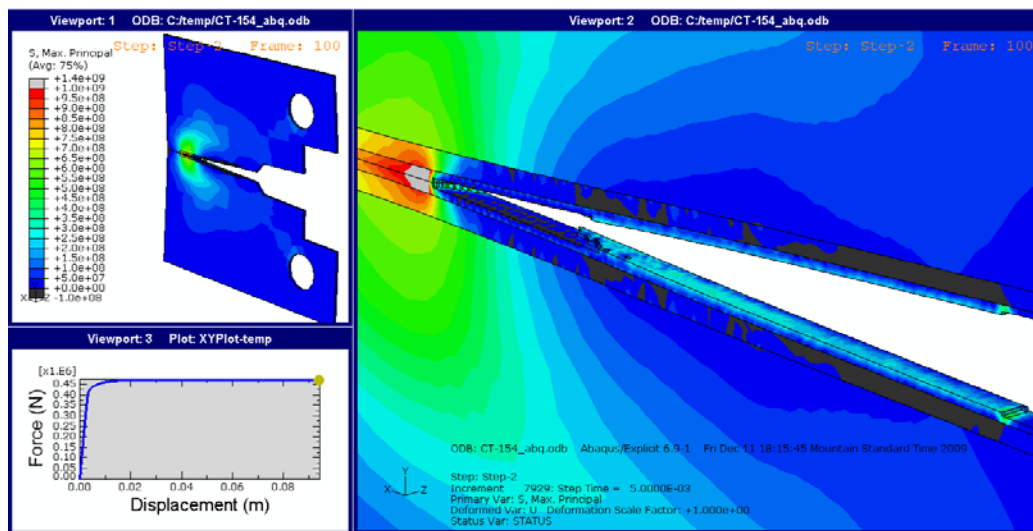


After brittle crack propagation

Figure 11. Sequence of snapshots, model with temperature gradient from 20 to 100°C, maximum principal stress (Pa), looking at the symmetry face. Deformations are not magnified.

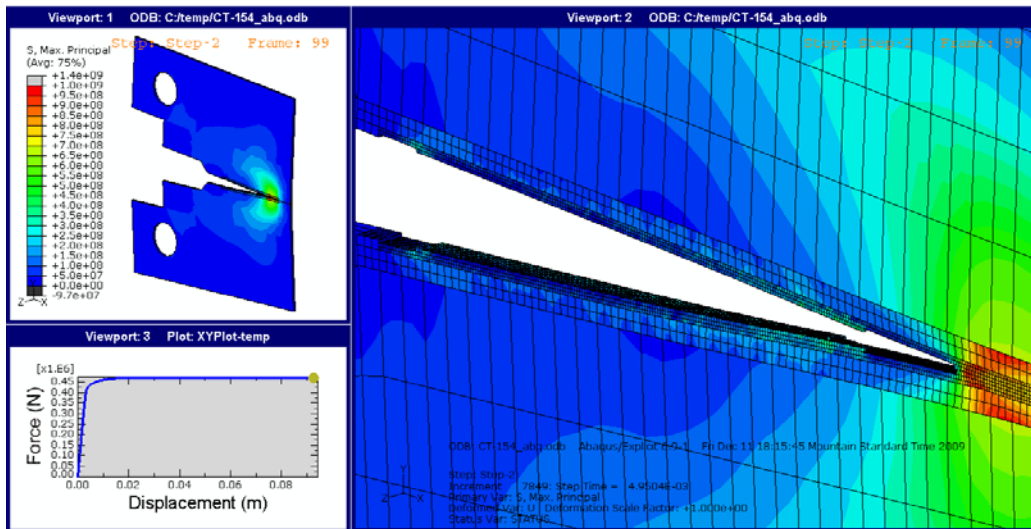


Transition from brittle to ductile crack propagation



At ductile crack arrest

Figure 11. Sequence of snapshots, model with temperature gradient from 20 to 100°C, maximum principal stress (Pa), looking at the symmetry face, (cont'd). Deformations are not magnified.



At ductile crack arrest

Figure 12. Snapshot, model with temperature gradient from 20 to 100°C, maximum principal stress (Pa), looking at the free face. Deformations are not magnified.

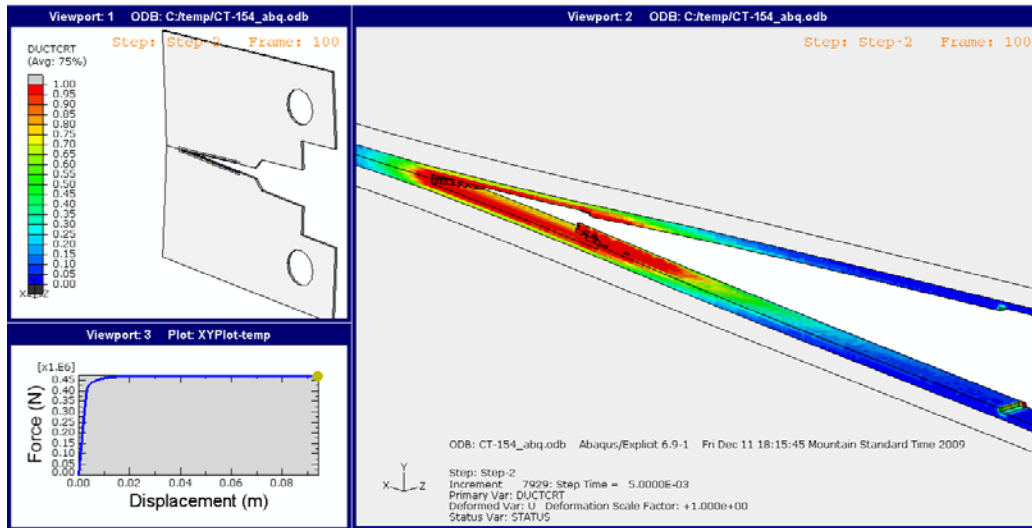


Figure 13. Snapshot, model with temperature gradient from 20 to 100°C, ductile damage initiation parameter, DUCTRT, looking at the symmetry face. Deformations are not magnified.

8. Conclusions

A methodology to simulate brittle crack initiation, followed by brittle or ductile propagation and brittle or ductile crack arrest was developed. Two material models, the Bao-Wierzbicki ductile failure criteria and cohesive contact, were used in this methodology. Parameters for the material models were calibrated by matching simulated toughness results and experimental results. Successful analyses demonstrated that this methodology can simulate brittle crack initiation, followed by brittle or ductile propagation and brittle or ductile crack arrest.

The following topics were suggested for investigation, in order to further develop this methodology:

- Studying dynamic effects and the impact of the duration of load application.
- Investigating the sensitivity of the results to crack propagation velocities.
- Quantifying mesh sensitivity.
- Validation of FEM against crack arrest experiments.

9. References

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